

# Assisted Problem Solving and Decompositions of Finite Automata

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# Assisted Problem Solving

- we consider the problem of recognizing a formal language
- how can this task be simplified, if we have some a priori information about the input?
- known approaches:
  - advice functions** - additional information is based on the length of the input
  - promise problems** - it is promised that inputs come only from some subset of  $\Sigma^*$

# Assisted Problem Solving - Advisors

- we engage an “advisor”, that processes the input prior to the “solver”
- solver then obtains some information about the results of the advisor’s computation
- we expect that having the information provided by the advisor, the solver’s task may become easier
- we also expect the advisor to be simpler than the original solver required for the task, otherwise the advisor would make the task trivial

# Assisted Problem Solving and DFAs

- the solver is a DFA trying to recognize some regular language
- the advisor is also a DFA
- we let the solver know some result of the advisor's computation on the input
  - did it accept the input?
  - what was the final state?
- to obtain nontrivial results we require both the advisor and the solver to be simpler than the minimal DFA for the language recognized
- the complexity measure used is the number of states
- this naturally leads to decompositions of finite automata

# S.P. Decompositions

- Hartmanis, Stearns - decompositions of sequential machines
- central concept: S.P. partition

## Definition

A partition  $\pi$  on the set of states of a sequential machine  $M$  is an S.P. partition, if

$$p \equiv_{\pi} q \Rightarrow (\forall a \in \Sigma; \delta(p, a) \equiv_{\pi} \delta(q, a))$$

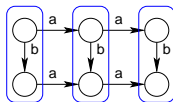


Figure: S.P. partition

- join and meet can be defined on S.P. partitions of  $M$ , they form a finite lattice (sublattice of the lattice of all partitions on the set of states of  $M$ )

# Parallel Decomposition of State Behavior

## Theorem (Hartmanis, Stearns)

*A sequential machine  $M$  has a parallel decomposition of state behavior iff there exist S.P. partitions  $\pi_1, \pi_2$  on the set of its states, such that  $\pi_1 \cdot \pi_2 = 0$ .*

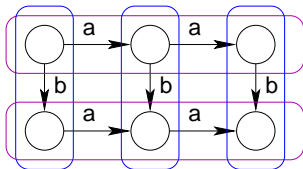


Figure: S.P. partitions  $\pi_1$  and  $\pi_2$ , such that  $\pi_1 \cdot \pi_2 = 0$ .

## New Types of Decomposition

- based on our motivation, we define new DFA decompositions
- what should the results of independent computations of both automata forming the decomposition say about the result of the computation of the original automaton?

### Definition

Decomposition of a DFA  $A$  into simpler DFAs  $A_1$  and  $A_2$ :

**SI-decomposition** – knowing the final states of  $A_1$  and  $A_2$ , we can determine the final state of  $A$

**AI-decomposition** – knowing whether  $A_1$  and  $A_2$  accept, we can determine whether  $A$  accepts

**wAI-decomposition** – knowing the final states of  $A_1$  and  $A_2$ , we can determine whether  $A$  accepts

# Decomposition of State Behavior

- adaptation of the notion from [Hartmanis, Stearns] for the DFA setting without losing the connection to the useful concept of S.P. partitions
- to be related to our new definitions

## Definition

$(A_1, A_2)$  forms an **SB-decomposition** of  $A$ , if  $\exists \alpha: K \xrightarrow{\text{inj.}} K_1 \times K_2$

$$(i) (\forall a \in \Sigma)(\forall q \in K); \alpha(\delta(q, a)) = (\delta_1(q_1, a), \delta_2(q_2, a))$$

where  $\alpha(q) = (q_1, q_2)$

$$(ii) \alpha(q_0) = (q_0^{(1)}, q_0^{(2)})$$



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and forms an **ASB-decomposition**, if moreover

$$(iii) (\forall q \in K); \alpha(q) \in F_1 \times F_2 \Leftrightarrow q \in F.$$

# Existence of the SB-decomposition

- the result of [Hartmanis, Stearns] holds also in the DFA setting

## Theorem

A DFA  $A$  has an SB-decomposition iff there exist S.P. partitions  $\pi_1, \pi_2$  on the set of its states, such that  $\pi_1 \cdot \pi_2 = 0$ .

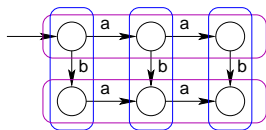


Figure: S.P. partitions  $\pi_1$  and  $\pi_2$ , such that  $\pi_1 \cdot \pi_2 = 0$ .

# Existence of the ASB-decomposition

- compared to SB-decompositions, we also have to take accepting states into account
- when deciding based on accepting behavior of  $A_1$  and  $A_2$ , we do not know, which of the accepting states was final, hence all possible pairs must lead to the same behavior in  $A$

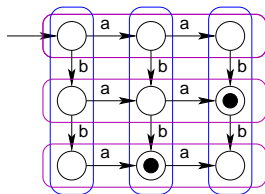


Figure: S.P. partitions  $\pi_1$  and  $\pi_2$  that do not induce an ASB-decomposition.

## Existence of the ASB-decomposition (contd.)

## Definition

Partitions  $\pi_1 = \{R_1, \dots, R_k\}$  and  $\pi_2 = \{S_1, \dots, S_l\}$  on the set of states of a DFA  $A$  **separate the final states**, if there exist indices  $i_1, \dots, i_r, j_1, \dots, j_s$ , such that

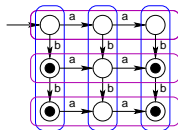
$$(R_{i_1} \cup \dots \cup R_{i_r}) \cap (S_{j_1} \cup \dots \cup S_{j_s}) = F.$$


Figure:  $\pi_1$  and  $\pi_2$  separate the final states.

## Theorem

*DFA  $A$  has an ASB-decomposition iff there exist S.P. partitions  $\pi_1$  and  $\pi_2$  on the set of its states, such that they separate the final states and it holds  $\pi_1 \cdot \pi_2 = 0$ .*

# Existence of the AI-decomposition and wAI-decomposition

- similar technique yields the following sufficient conditions for the existence of the AI-decomposition and wAI-decomposition:

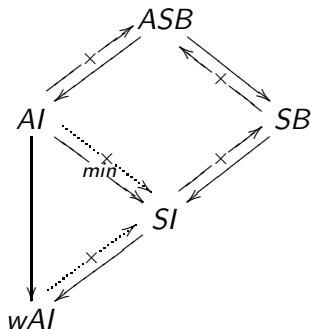
## Theorem

*Let  $A$  be a DFA and let  $\pi_1$  and  $\pi_2$  be S.P. partitions on the set of its states, such that they separate the final states of  $A$ . Then  $A$  has an AI-decomposition.*

## Theorem

*Let  $A$  be a DFA and let  $\pi_1$  and  $\pi_2$  be S.P. partitions on the set of its states, such that it holds  $\pi_1 \cdot \pi_2 \preceq \{F, K - F\}$ . Then  $A$  has an wAI-decomposition.*

## Relations between types of decomposition



$A \longrightarrow B$  : every A-decomposition is also a B-decomposition

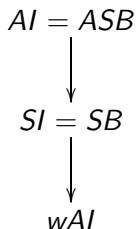
$A \xrightarrow{min} B$  : every A-decomposition of a minimal DFA is also a B-decomposition

$A \xrightarrow{x} B$  : not every A-decomposition is also a B-decomposition

$A \xrightarrow{x} B$  : there exists a DFA that has a nontrivial A-decomposition but does not have a nontrivial B-decomposition

# Perfectly Decomposable Automata

$(A_1, A_2)$  is a **perfect** decomposition of  $A$ , if  $|K_1| \cdot |K_2| = |K|$ .



- for DFAs without unreachable states, each perfect **SI**-decomposition is also a perfect **SB**-decomposition
- for minimal DFAs, each perfect **AI**-decomposition is also a perfect **ASB**-decomposition
- hence, we can use the derived necessary and sufficient conditions for the existence of **ASB**- and **SB**-decompositions to decide the existence of perfect **AI**- a **SI**-decompositions

# Decomposability of the Minimal DFA

- How is the decomposability of a DFA related to the decomposability of the corresponding minimal automaton?

## Theorem

Let  $A$  be a DFA and  $A_{min}$  be the minimal DFA equivalent to  $A$ .  
Then

- 1 If  $(A_1, A_2)$  form an *AI*-decomposition (*SI*-decomposition, *wAI*-decomposition)  $A$ , then they form also a decomposition of  $A_{min}$  of the same type.
- 2 If  $(A_1, A_2)$  form an *SB*-decomposition  $A$  and the *S.P.*-lattice of DFA  $A$  is distributive, then there also exists an *SB*-decomposition of  $A_{min}$ , such that its  $i^{th}$  DFA has at most as many states as  $A_i$ ,  $i \in \{1, 2\}$ .





# Achievable Degrees of Decomposability

- we know that undecomposable and perfectly decomposable automata exist
- what is the situation between these two extreme points?

## Theorem

*Let  $n \in \mathbb{N}$  be such that  $n = k + r \cdot s$ , where  $r, s, k \in \mathbb{N}$ ,  $r, s \geq 2$ . Then there exists a minimal DFA  $A$  consisting of  $n$  states, such that it has only one nontrivial nonredundant **SB**-decomposition (**ASB**-decomposition) up to the order of the automata in the decomposition, and this decomposition consists of automata with  $k + r$  and  $k + s$  states.*

# Sketch of the Proof

## Lemma

For each  $r, s \in \mathbb{N}$ ,  $r, s \geq 2$ , there exists a minimal DFA  $A$  consisting of  $r \cdot s$  states and having only one nontrivial nonredundant  $SB$ -decomposition ( $ASB$ -decomposition) up to the order of automata, consisting of automata having  $r$  and  $s$  states.

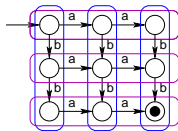


Figure: An example for  $r = s = 3$ .

## Sketch of the Proof (contd.)

## Lemma

Let  $A$  be a DFA consisting of  $n$  reachable states. Let  $A'$  be its  $k$ -extension. Then  $A$  has a nontrivial nonredundant  $SB$ -decomposition ( $ASB$ -decomposition) consisting of automata having  $r$  and  $s$  states iff  $A'$  has a nontrivial nonredundant decomposition of the same type, consisting of automata having  $k + r$  and  $k + s$  states.

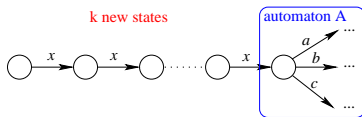


Figure: The  $k$ -extension of an automaton  $A$ .

# Summary

Our contribution:

- initiating the study of assisted problem solving
- applying it to the world of finite automata
  - defining new DFA decompositions modelling this intuitive concept
  - deriving conditions for the existence of these decompositions
  - inspecting the notion of perfect decomposability
  - exploring the decomposability of the corresponding minimal DFA
  - inspecting the various degrees of decomposability that can be achieved

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Thank you for your attention.