Motivation

object-capability paradigm

Pict specific detail

Taming of Pic

Open Problems

from π -calculus to Pict

Taming of Pict

Matej Košík

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January 21, 2008

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- ▶ POLA can be obeyed without discomfort
- expressivness
- elegance
- efficiency
- smaller TCB

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Limitations

▶ source code of all parts of the system must be available

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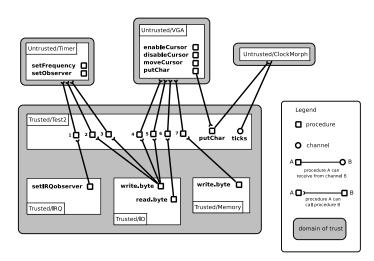
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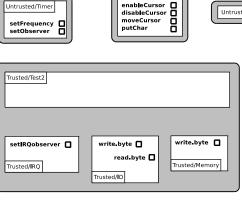
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Untrusted/VGA





Legend

procedure

channel

hopocedure A can receive from channel B

procedure A can a call procedure B

domain of trust

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The Problem: Required authority of the untrusted VGA driver

- ▶ to read from the 0x3D5 I/O register
- ▶ to read from the 0x3D4 I/O register
- ▶ to write to the 0x3D4 I/O register
- to write to the frame buffer

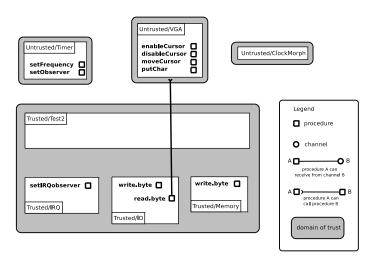
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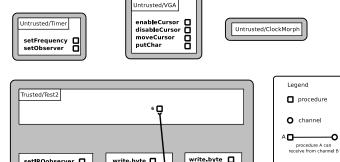
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Trusted/Memory

write byte read byte

Trusted/IO

setIRQobserver

Trusted/IRQ

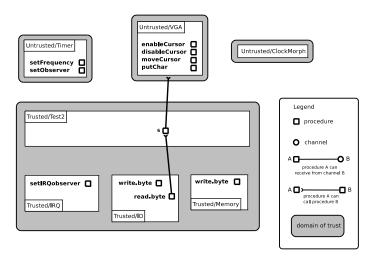
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call procedure B

domain of trust



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io.read.byte

() = (io.read.byte 981)

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io.read.byte

\() = (io.read.byte 981)

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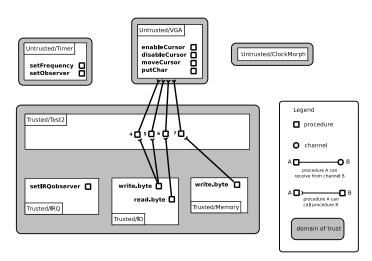
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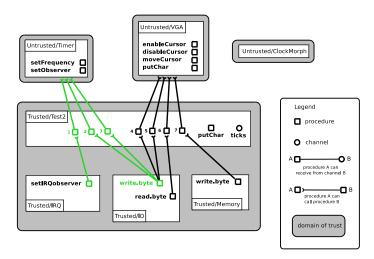
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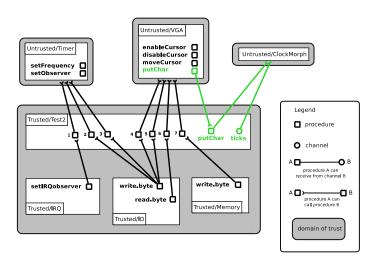
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From π-calculus



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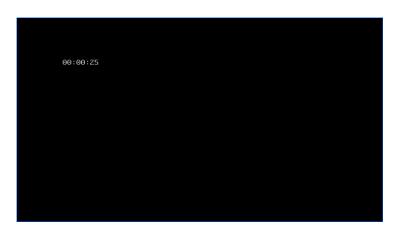
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Powerboxed ClockMorph



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From π-calculus to Pict

```
kosik@debian:~/work/noweb/ping$ sudo ./ping 209.85.135.103
28 bytes from 209.85.135.103: icmp_seq=1
28 butes from 209.85.135.103: icmp_sea=2
28 bytes from 209.85.135.103: icmp_seq=3
28 bytes from 209.85.135.103: icmp_seq=4
28 butes from 209.85.135.103: icmp_sea=5
28 bytes from 209.85.135.103: icmp_seq=6
28 bytes from 209.85.135.103: icmp_seq=7
28 butes from 209.85.135.103: icmp_seq=8
28 bytes from 209.85.135.103: icmp_seq=9
28 butes from 209.85.135.103: icmp_sea=10
28 bytes from 209.85.135.103: icmp_seq=11
28 bytes from 209.85.135.103: icmp_seq=12
28 butes from 209.85.135.103: icmp_seq=13
  bytes from 209.85.135.103: icmp_seq=14
28 bytes from 209.85.135.103: icmp_seq=15
28 butes from 209.85.135.103: icmp_seq=16
28 bytes from 209.85.135.103: icmp_seq=17
28 bytes from 209.85.135.103: icmp_seq=18
28 bytes from 209.85.135.103: icmp_seq=19
28 bytes from 209.85.135.103: icmp_seq=20
UNIX signal 2 was received. Terminating by default.
kosik@dĕbian:~/work/noweb/ping$ ∏
```

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Reference Graph Dynamics

 $[1, \S 9.2]$

- connectivity by initial conditions
- connectivity by parenthood
- connectivity by introduction
- connectivity by endowment

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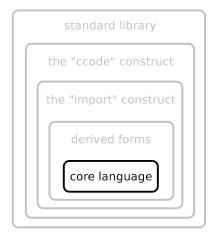
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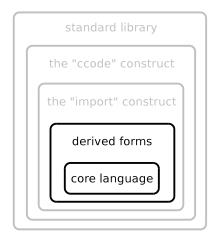
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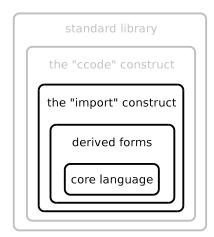
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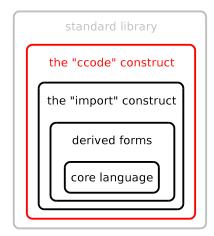
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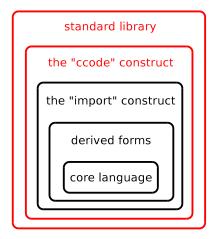
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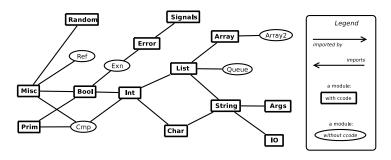
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The original standard library



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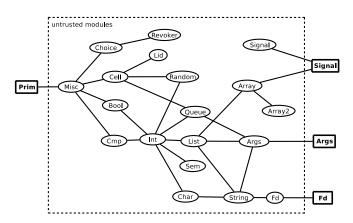
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Refactored library



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imported by

untrusted

trusted

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- any untrusted component can consume as much memory as it wishes
- any untrusted component can consume as much CPU ticks as it wishes
- formal methods can significantly refine assessments of upperbound of threat we face

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Mark Samuel Miller.

Robust Composition: Towards a Unified Approach to Access Control and Concurrency Control.

PhD thesis, Johns Hopkins University, Baltimore, Maryland, USA, May 2006.

Robin Milner.

Communicating and Mobile Systems: The π -calculus. Cambridge University Press, 1999.

$$\pi ::= \overline{x}y \mid x(z) \mid \tau \mid [x = y]\pi$$

$$\mathsf{P} ::= (\mathsf{P} \mid \mathsf{P}) \mid \nu \mathsf{z} \mathsf{P} \mid !\mathsf{P} \mid \mathsf{M}$$

$$M ::= 0 | \pi.P | M + M$$

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$$\pi$$
 ::= $\overline{x}y \mid x(z) \mid \tau$

$$\mathsf{P} \ ::= \ (\mathsf{P} \,|\, \mathsf{P}) \,|\, \nu \mathsf{z} \mathsf{P} \,|\, \mathsf{!P} \,|\, \mathsf{M}$$

$$M ::= 0 | \pi.P | M + M$$

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$$\pi ::= \overline{x}y \mid x(z)$$

$$P ::= (P|P) \mid \nu z P \mid !P \mid M$$

$$\mathsf{M} ::= 0 \mid \pi.\mathsf{P} \mid \mathsf{M} + \mathsf{M}$$

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$$\pi ::= \overline{x}y \mid x(z)$$

$$\mathsf{P} \ ::= \ (\mathsf{P} \,|\, \mathsf{P}) \,|\, \nu \mathsf{z} \mathsf{P} \,|\, \mathsf{!P} \,|\, \mathsf{M}$$

$$\mathsf{M} ::= \mathsf{0} \mid \pi.\mathsf{P}$$

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$$\mathsf{P} \ ::= \ (\mathsf{P} \,|\, \mathsf{P}) \,|\, \nu \mathsf{z} \mathsf{P} \,|\, \mathsf{!P} \,|\, \mathsf{M}$$

$$M ::= 0 \mid \overline{x}y.0 \mid x(z).P$$

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$$\mathsf{P} \quad ::= \quad \left(\mathsf{P} \mid \mathsf{P}\right) \mid \; \nu \mathsf{z} \mathsf{P} \; \mid \; \nu \mathsf{x} \left(! \mathsf{x}(\mathsf{z}).\mathsf{P} \mid \mathsf{P} \right) \; \mid$$

 $\mathsf{M} \ ::= \ \mathbf{0} \ | \ \overline{\mathsf{x}} \mathsf{y.0} \ | \ \mathsf{x(z).P}$

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